# Using smoke and mirrors to compile a functional programming language to efficient GPU code

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- Troels Henriksen.
- Assistant professor researcher at the Department of Computer Science at the University of Copenhagen (DIKU).
- All this is joint work with Cosmin Oancea, Philip Munksgaard, Robert Schenck, Martin Elsman, and various open source contributors way.

#### When I was first taught functional programming, I was told it would be the future because it makes parallel execution trivial.

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E.g. f(g(x), h(y)) — in a pure language, g(x) and h(y) can be executed in parallel.

It's the future now—where's all the parallel functional programming?

- **Counterclaim: it has!** Lots of parallel and concurrent programming libraries baed on functional concepts:
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- **Counterclaim: it has!** Lots of parallel and concurrent programming libraries baed on functional concepts:
  - Akka (Scala), TensorFlow (Python), Accelerate (Haskell)...
- But that's not how I understood it!
  - GPUs are modern parallel computers...
  - ...so why can't my compiler automatically turn my Scala/Haskell/OCaml program into e.g. fast GPU code?

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#### Parallelising small nuggets of work is not efficient on current computers.

- ▶ f(g(x),h(y))
- Some people work on hardware designed for functional programming, but I want to use existing, consumer parallel hardware, such as GPUs.

#### The big question

How do we go from *idiomatic functional code* to the kind of low-level programming style expected by a GPU?

- Some kinds of functional programming are not suited for GPU parallelisation.
  - E.g. tiny recursive steps over sequential data structures like lists.
- But bulk data transformations with higher order functions is very well suited!
  - ▶ map



- ▶ scan
- filter

▶ ...

(Incidentally, that kind of style is also what most high level parallel libraries are designed for.)

## This is how I want to write parallel programs

def dotprod [n] (x: [n]f32) (y: [n]f32) =
f32.sum (map2 (\*) x y)

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- This is Futhark—a small parallel functional language in the ML tradition that we develop at DIKU.
- Compiles to GPU or CPU code.
- By design very much a "least common denominator" language.

## Let's talk about GPUs

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```
kernel (int* arr) {
   var i = get_thread_id();
   var x = arr[i];
   if (x < 0) {
      arr[i] = -x;
   }
}</pre>
```

- Threads are split into warps, which execute in lockstep.
- **Regularity** is important.
- Memory access usually the bottleneck.

#### Warp of threads

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Memory

#### Warp of threads



#### Warp of threads



#### Thread warp

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Memory











## **Compiling a functional language to GPU**

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#### The trick

Solve an easier problem by removing some language features and hope programmers won't notice.

## Let's talk about value representation

#### Most fundamental principle

Futhark **unboxes** all non-arrays to keep them in registers.

- A triple (a, b, c) is treated as three distinct values.
- A record {x: f32, y: f32} is syntactic sugar for a tuple (f32, f32)

#### **def** swap 'a 'b (x: a, y: b) = (y, x)

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```
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```

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**def** swap\_i32\_bool (x: bool, y: i32) = (y,x)

... swap\_i32\_bool (1,true)...

### Let's talk about arrays

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$$A = \begin{bmatrix} [1, 2, 3, 4, 5, 6], \\ [7, 8, 9, 10, 11, 12], \\ [13, 14, 15, 16, 17, 18], \\ [19, 20, 21, 22, 23, 24] \end{bmatrix}$$
#### Let's talk about arrays

$$A = \begin{bmatrix} [1, 2, 3, 4, 5, 6], \\ [7, 8, 9, 10, 11, 12], \\ [13, 14, 15, 16, 17, 18], \\ [19, 20, 21, 22, 23, 24] \end{bmatrix}$$

#### map (foldl (+) 0) A





























































- We provide a **programming model** based on "arrays of arrays".
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- But in-memory representation is dense, in some layout decided on compiler.
- Key restriction: arrays must be *regular*.

[[1,2,3], [4,5]] -- Forbidden!

Verified by the type checker using a size-dependent type system .

#### But it's not just about multidimensional arrays

 Suppose we have n threads and they each sequential construct an array with m elements.

map (\x -> ...
let b : [m]i32 = ...
) xs

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```

If each thread is given its own memory block, then we're back to chasing pointers and uncoalesced memory.





And we store arrays from different threads interleaved, to get coalesced access.



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Consider arrays of type [] (i32, i8). Since an i32 is four bytes and a i8 is one byte, how should Futhark store this in memory?

Problem: Unaligned access.

Problem: Waste of memory.

And both lead to uncoalesced access when the tuples are large.

## **Tuples of arrays**

#### Representation

Array type [n] (a, b, c...) is represented in memory as ([n]a, [n]b, [n]c...), i.e. as multiple arrays, each containing only primitive values.

- Common (and crucial) transformation.
- Called "struct of arrays" in legacy languages.
- Automatically done by the Futhark compiler.
- Only affects internal language.

#### **Higher-order functions are problematic**

- Normally implemented via function pointers.
- GPUs do not efficiently support function pointers.

# Fortunately, the 70s were full of people who did not like function pointers either.

(Futhark work by Anders Kiel Hovgaard)

## Defunctionalisation (Reynolds, 1972)

John Reynolds: "Definitional interpreters for higher-order programming languages"

Replace lambdas by tagged data value that captures free variables:

 $\lambda x.x + y \Longrightarrow \operatorname{Lam} y$
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Replace application by case dispatching over these functions:

 $f a \implies$  case f of Lam1...  $\rightarrow$  ... Lam2...  $\rightarrow$  ... Lam $I y \rightarrow a + y$ 

. . .

- Branch divergence on GPUs.
- Arrays of these things are likely inefficient.

Conditionals may not produce functions:

```
let f = if b1 then \x -> foo
    else if b N then \x -> bar
    else ... \x -> baz
in... f y
```

- Which function **f** is applied?
- To defunctionalise without introducing branching, we must restrict conditionals from returning functions.
- We require that branches have order zero type.

### Arrays may not contain functions

```
let fs = [\y -> y+a, \z -> z*b, ...]
in... fs[n] 5
```

Which function fs[n] is applied?

- And a few similar restrictions for other language constructs...
- Restricting the language enables better code generation.
- Important: the restrictions are easy to understand, checked in the type checker, and are often not a hindrance in practice

## Sum types (work by Robert Schenk)

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#### The usual representation is tag plus pointer

-- Constructor names are #-prefixed in Futhark **type** vec = #vec2 {x: f32, y: f32} | #vec3 {x: f32, y: f32, z: f32}



Composes well, and never uses more space than necessary.

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### Irregular representation requires unpredictable allocations

Where do we get the memory for the #some payload?

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```
if x >= 0 then #some (sqrt x)
        else #none
```

Where do we get the memory for the #some payload?

#### Memory access becomes uncoalesced

[#some 1, #none, #some 3, ...]

When map-ing, no guarantee that the payloads are adjacent in memory.

#### We translate sum types to tuples.

```
type vec2 = {x: f32, y: f32}
type vec3 = {x: f32, y: f32, z: f32}
type vec = #vec2 vec2 | #vec3 vec3
```

becomes

```
type vec = (i8, vec2, vec3)
```

with the 18 encoding the constructor.

Insert dummy values for unused constructor payloads.

Rust implements sum types by making their payload the size of the *maximum* of the constructor payloads.

tag payload bytes

 $\#some (\#vec2 \{x=1.0, y=2.0\})$ 

#some	#vec2	1.0	2.0	-
-------	-------	-----	-----	---

1.0

2.0

3.0

#none

#none

Rust implements sum types by making their payload the size of the *maximum* of the constructor payloads.

tag payload bytes

 $\#some (\#vec2 \{x=1.0, y=2.0\})$ 

#none

#some	#vec2	1.0	2.0	-
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3.0

#none

Unfortunately doesn't work with the tuple-of-arrays transformation.

#### Deduplication exploits redundancies across constructors



#### Deduplication gives $2 \times$ speedup on a ray tracer

**type** vec3 = {x: f32, y: f32, z: f32}

https://github.com/athas/raytracinginoneweekendinfuthark

# Matrix multiplication

**def** dotprod x y = f32.sum (map2 (\*) x y)

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Multiplying 4096  $\times$  1024 and 1024  $\times$  4096 matrices on A100 GPU

Futhark: 3880µs

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Multiplying 4096  $\times$  1024 and 1024  $\times$  4096 matrices on A100 GPU

Futhark:  $3880\mu s$ cuBLAS:  $1899\mu s$  (2 × faster than Futhark) Benchmarks based on the Monte Carlo neutron transport algorithm.

XSBench Futhark: Original: RSBench Futhark: Original:

Ported from hand-written CUDA to Futhark.

Benchmarks based on the Monte Carlo neutron transport algorithm.

 XSBench Futhark: 142ms Original: 142ms
 RSBench Futhark: 1342ms Original: 1108ms (1.21 × faster than Futhark)

Ported from hand-written CUDA to Futhark.

- Functional programming *is* good for parallelism.
  - But many of its classical features are not.
- Locality and regularity are central to truly high performance.
  - And functional programming makes it easy to build irregular things.
- Optimisations and transformations are known that can help.
  - But they make tradeoffs that are not right for every situation.
- Things are much easier when you restrict the input language.

Go try Futhark!

https://futhark-lang.org